

# Interpolating Manifestly Covariant Conformal Algebra $(1 + 1)$ between IFD and LFD

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October 20, 2023

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# Conformal Transformations

Let us consider a flat space in  $d$  dimensions and transformations thereof, which locally preserves the angle between any two lines. A conformal transformation is a smooth, invertible map  $x \rightarrow x'$  such that

$$g'_{\rho\sigma}(x') \frac{\partial x'^{\rho}}{\partial x^{\mu}} \frac{\partial x'^{\sigma}}{\partial x^{\nu}} = \Lambda(x) g_{\mu\nu}(x), \quad (1.1)$$

where the positive function  $\Lambda(x)$  is called the scale factor.

Furthermore, for flat spaces, the scale factor  $\Lambda(x) = 1$  corresponds to the Poincaré group consisting of translations and rotations, respectively, Lorentz transformations.

Let us next consider the infinitesimal coordinate transformations which up to first order in a small parameter  $\epsilon(x) \ll 1$  read

$$x'^{\rho} = x^{\rho} + \epsilon^{\rho}(x) + \mathcal{O}(\epsilon^2). \quad (1.2)$$

# Conformal Transformations

For  $d \geq 3$ , there are ONLY 4 classes of solutions for  $\epsilon_\mu(x)$  of  $x'_\mu = x_\mu + \epsilon_\mu(x) + \mathcal{O}(\epsilon^2)$ .

$$\text{(Infinitesimal Translation)} \quad \epsilon^\mu(x) = a^\mu \quad (\text{constant}) \quad (1.3)$$

$$\text{(Infinitesimal Rotation)} \quad \epsilon^\mu(x) = M_\nu^\mu x^\nu \quad (1.4)$$

$$\text{(Infinitesimal Scaling)} \quad \epsilon^\mu(x) = \lambda x^\mu \quad (1.5)$$

$$\text{(Infinitesimal SCT)} \quad \epsilon^\mu(x) = 2(b \cdot x)x^\mu - x^2 b^\mu \quad (1.6)$$

The Finite conformal transformations are:

$$\text{(translation)} \quad x'^\mu = x^\mu + a^\mu$$

$$\text{(rotation)} \quad x'^\mu = M_\nu^\mu x^\nu$$

$$\text{(dilatation)} \quad x'^\mu = \alpha x^\mu$$

$$\text{(SCT)} \quad x'^\mu = \frac{x^\mu - b^\mu x^2}{1 - 2b \cdot x + b^2 x^2}$$

Inversions are given by

$$\boxed{x^\mu} \longrightarrow \boxed{x'^\mu = \frac{x^\mu}{x^2}} \quad (1.7)$$

The SCTs can be understood as an inversion of  $x^\mu$ , followed by a translation  $b^\mu$ , and followed again by an inversion.

$$\boxed{x^\mu} \longrightarrow \boxed{x'^\mu = \frac{x^\mu}{x^2}} \longrightarrow \boxed{x''^\mu = \frac{x^\mu}{x^2} - b^\mu} \longrightarrow \boxed{x'''^\mu = \frac{\frac{x^\mu}{x^2} - b^\mu}{\left(\frac{x^\mu}{x^2} - b^\mu\right)^2} = \frac{x^\mu - b^\mu x^2}{1 - 2b \cdot x + b^2 x^2}}$$

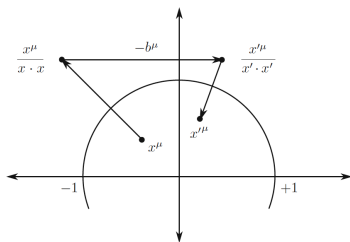


Figure 1: Illustration of a finite SCT

# Conformal algebra

The generators of conformal transformations are:  $P^\mu = i\partial^\mu$  (translation),  $M^{\mu\nu} = i(x^\mu\partial^\nu - x^\nu\partial^\mu)$  (rotation),  $D = ix_\mu\partial^\mu$  (dilation or scaling), and  $\mathfrak{K}^\mu = i(2x^\mu x_\nu\partial^\nu - x^2\partial^\mu)$  (SCT).

Therefore, the full Conformal algebra is given by

$$[P_\mu, P_\nu] = 0; [\mathfrak{K}_\mu, \mathfrak{K}_\nu] = 0;$$

$$[D, P_\mu] = -iP_\mu; [D, \mathfrak{K}_\mu] = i\mathfrak{K}_\mu;$$

$$[P_\rho, M_{\mu\nu}] = i(g_{\rho\mu}P_\nu - g_{\rho\nu}P_\mu);$$

$$[\mathfrak{K}_\rho, M_{\mu\nu}] = i(g_{\rho\mu}\mathfrak{K}_\nu - g_{\rho\nu}\mathfrak{K}_\mu);$$

$$[M_{\alpha\beta}, M_{\rho\sigma}] = -i(g_{\beta\sigma}M_{\alpha\rho} - g_{\beta\rho}M_{\alpha\sigma} + g_{\alpha\rho}M_{\beta\sigma} - g_{\alpha\sigma}M_{\beta\rho});$$

$$[\mathfrak{K}_\mu, P_\nu] = -2i(g_{\mu\nu}D + M_{\mu\nu}); [D, M_{\mu\nu}] = 0.$$

# Full conformal algebra in Interpolation

A comprehensive table of the **105 commutation** relations among the co-variant components of the Conformal generators is presented below:

|                      | $P_{\pm}$                 | $P_1$       | $P_2$       | $K^3$   | $D^1$                 | $D^2$              | $J^3$              | $K^1$                 | $K^2$                 | $P_{\pm}$                 | $\mathfrak{R}_{\pm}$                           | $\mathfrak{R}_1$       | $\mathfrak{R}_2$       | $\mathfrak{R}_{\pm}$                            | $D$                    |
|----------------------|---------------------------|-------------|-------------|---|-----------------------|--------------------|--------------------|-----------------------|-----------------------|---------------------------|--|------------------------|------------------------|---|------------------------|
| $P_{\pm}$            | 0                         | 0           | 0           | $i(CP_{\pm} - SP_{\pm})$                        | $iCP_1$               | $iCP_2$            | 0                  | $iSP_1$               | $iSP_2$               | 0                         | $2iCD$   | $-2iD^1$               | $-2iD^2$               | $2i(SD - K^3)$                                  | $iP_{\pm}$             |
| $P_1$                | 0                         | 0           | 0           | 0   | $iP_{\pm}$            | 0                  | $-iP_2$            | $iP_{\pm}$            | 0                     | 0                         | $2iD^1$  | $-2iD$                 | $-2iJ^3$               | $2iK^1$   | $iP_1$                 |
| $P_2$                | 0                         | 0           | 0           | 0   | 0                     | $iP_{\pm}$         | $iP_1$             | 0                     | $iP_{\pm}$            | 0                         | $2iD^2$  | $2iJ^3$                | $-2iD$                 | $2iK^2$   | $iP_2$                 |
| $K^3$                | $-i(CP_{\pm} - SP_{\pm})$ | 0           | 0           | 0   | $iSD^1 - iCK^1$       | $iSD^2 - iCK^2$    | 0                  | $-iSK^1 - iCD^1$      | $-iSK^2 - iCD^2$      | $-i(SP_{\pm} + CP_{\pm})$ | $i(S\mathfrak{R}_{\pm} - C\mathfrak{R}_{\pm})$ | 0                      | 0                      | $-i(C\mathfrak{R}_{\pm} + S\mathfrak{R}_{\pm})$ | 0                      |
| $D^1$                | $-iCP_1$                  | $-iP_{\pm}$ | 0           | $-iSD^1 + iCK^1$                                | 0                     | $-iCJ^3$           | $-iD^2$            | $iK^3$                | $-iSJ^3$              | $-iSP_1$                  | $-iC\mathfrak{R}_1$                            | $-i\mathfrak{R}_{\pm}$ | 0                      | $-iS\mathfrak{R}_1$                             | 0                      |
| $D^2$                | $-iCP_2$                  | 0           | $-iP_{\pm}$ | $-iSD^2 + iCK^2$                                | $iCJ^3$               | 0                  | $iD^1$             | $iSJ^3$               | $iK^3$                | $-iSP_2$                  | $-iC\mathfrak{R}_2$                            | 0                      | $-i\mathfrak{R}_{\pm}$ | $-iS\mathfrak{R}_2$                             | 0                      |
| $J^3$                | 0                         | $iP_2$      | $-iP_1$     | 0   | $iD^2$                | $-iD^1$            | 0                  | $iK^2$                | $-iK^1$               | 0                         | 0  | $i\mathfrak{R}_2$      | $-i\mathfrak{R}_1$     | 0   | 0                      |
| $K^1$                | $-iSP_1$                  | $-iP_{\pm}$ | 0           | $iSK^1 + iCD^1$                                 | $-iK^3$               | $-iSJ^3$           | $-iK^2$            | 0                     | $iCJ^3$               | $iCP_1$                   | $-iS\mathfrak{R}_1$                            | $-i\mathfrak{R}_{\pm}$ | 0                      | $iC\mathfrak{R}_1$                              | 0                      |
| $K^2$                | $-iSP_2$                  | 0           | $-iP_{\pm}$ | $iSK^2 + iCD^2$                                 | $iSJ^3$               | $-iK^3$            | $iK^1$             | $-iCJ^3$              | 0                     | $iCP_2$                   | $-iS\mathfrak{R}_2$                            | 0                      | $-i\mathfrak{R}_{\pm}$ | $iC\mathfrak{R}_2$                              | 0                      |
| $P_{\pm}$            | 0                         | 0           | 0           | $i(SP_{\pm} + CP_{\pm})$                        | $iSP_1$               | $iSP_2$            | 0                  | $-iCP_1$              | $-iCP_2$              | 0                         | $2i(SD + K^3)$                                 | $-2iK^1$               | $-2iK^2$               | $-2iCD$   | $iP_{\pm}$             |
| $\mathfrak{R}_{\pm}$ | $-2iCD$                   | $-2iD^1$    | $-2iD^2$    | $-i(S\mathfrak{R}_{\pm} - C\mathfrak{R}_{\pm})$ | $iC\mathfrak{R}_1$    | $iC\mathfrak{R}_2$ | 0                  | $iS\mathfrak{R}_1$    | $iS\mathfrak{R}_2$    | $-2i(SD + K^3)$           | 0  | 0                      | 0                      | 0   | $-i\mathfrak{R}_{\pm}$ |
| $\mathfrak{R}_1$     | $2iD^1$                   | $2iD$       | $-2iJ^3$    | 0   | $i\mathfrak{R}_{\pm}$ | 0                  | $-i\mathfrak{R}_2$ | $i\mathfrak{R}_{\pm}$ | 0                     | $2iK^1$                   | 0  | 0                      | 0                      | 0   | $-i\mathfrak{R}_1$     |
| $\mathfrak{R}_2$     | $2iD^2$                   | $2iJ^3$     | $2iD$       | 0   | 0                     | $i\mathfrak{R}_2$  | $i\mathfrak{R}_1$  | 0                     | $i\mathfrak{R}_{\pm}$ | $2iK^2$                   | 0  | 0                      | 0                      | 0   | $-i\mathfrak{R}_2$     |
| $\mathfrak{R}_{\pm}$ | $-2i(SD - K^3)$           | $-2iK^1$    | $-2iK^2$    | $i(C\mathfrak{R}_{\pm} + S\mathfrak{R}_{\pm})$  | $iS\mathfrak{R}_1$    | $iS\mathfrak{R}_2$ | 0                  | $-iC\mathfrak{R}_1$   | $-iC\mathfrak{R}_2$   | $2iCD$                    | 0  | 0                      | 0                      | 0   | $-i\mathfrak{R}_{\pm}$ |
| $D$                  | $-iP_{\pm}$               | $-iP_1$     | $-iP_2$     | 0   | 0                     | 0                  | 0                  | 0                     | 0                     | $-iP_{\pm}$               | $i\mathfrak{R}_{\pm}$                          | $i\mathfrak{R}_1$      | $i\mathfrak{R}_2$      | $i\mathfrak{R}_{\pm}$                           | 0                      |

# Kinematic and dynamic generators of the Conformal group<sup>12</sup>

The generators of conformal transformations:

$$\text{(translation)} \quad P^{\hat{\mu}} = i\partial^{\hat{\mu}} \quad (2.1)$$

$$\text{(dilation)} \quad D = ix_{\hat{\rho}}\partial^{\hat{\rho}} \quad (2.2)$$

$$\text{(rotation)} \quad M^{\hat{\mu}\hat{\nu}} = i(x^{\hat{\mu}}\partial^{\hat{\nu}} - x^{\hat{\nu}}\partial^{\hat{\mu}}) \quad (2.3)$$

$$\text{(SCT)} \quad \mathfrak{K}^{\hat{\mu}} = i(2x^{\hat{\mu}}x_{\hat{\nu}}\partial^{\hat{\nu}} - x^2\partial^{\hat{\mu}}) \quad (2.4)$$

Since  $[\mathfrak{K}^{\hat{\mu}}, x^{\hat{\nu}}] = i(2x^{\hat{\nu}}x^{\hat{\mu}} - (x^{\hat{\alpha}}.x_{\hat{\alpha}})\mathbb{C}) \rightarrow i(x^0.x^0 + \vec{x}.\vec{x})$  as  $\delta \rightarrow 0$ , and  $[\mathfrak{K}^{\hat{\mu}}, x^{\hat{\nu}}] = i(2x^{\hat{\nu}}x^{\hat{\mu}} - (x^{\hat{\alpha}}.x_{\hat{\alpha}})\mathbb{C}) \rightarrow i(2x^+ . x^+)$  as  $\delta \rightarrow \pi/4$ , the conformal generator (LF time component)  $\mathfrak{K}_-$  is Kinematic in LFD, but Dynamic in IFD. And  $[D, x^{\hat{\mu}}] = ix^{\hat{\mu}}$ , so  $D$  is always Kinematic in both IFD and LFD.

| Interpolation angle     | Kinematic  | Dynamic  |
|-------------------------|--|--|
| $\delta = 0$            | $\mathcal{K}^1 = -J^2, \mathcal{K}^2 = J^1, J^3, P^1, P^2, P^3, D$                       | $\mathcal{D}^1 = -K^1, \mathcal{D}^2 = -K^2, K^3, P^0, \mathfrak{K}_0, \mathfrak{K}_1, \mathfrak{K}_2, \mathfrak{K}_3$ |
| $0 \leq \delta < \pi/4$ | $\mathcal{K}^1, \mathcal{K}^2, J^3, P^1, P^2, P_-, D$                                    | $\mathcal{D}^1, \mathcal{D}^2, K^3, P_+, \mathfrak{K}_+, \mathfrak{K}_1, \mathfrak{K}_2, \mathfrak{K}_-$               |
| $\delta = \pi/4$        | $\mathcal{K}^1 = -E^1, \mathcal{K}^2 = -E^2, J^3, K^3, P^1, P^2, P_-, D, \mathfrak{K}_-$ | $\mathcal{D}^1 = -F^1, \mathcal{D}^2 = -F^2, P_+, \mathfrak{K}_+, \mathfrak{K}_1, \mathfrak{K}_2$                      |

<sup>1</sup>Chueng-Ryong Ji and Chad Mitchell, Phys. Rev. **D 64**, 085013 (2001).

<sup>2</sup>Chueng-Ryong Ji, Ziyue Li, and Alfredo Takashi Suzuki, Phys. Rev. **D 91**, 065020 (2015).



# Boost as Rotations in 4D

The 4D Angular momentum tensor is given by:

$$M_{\mu\nu} = i(x_\mu\partial_\nu - x_\nu\partial_\mu) = \begin{pmatrix} 0 & -K^1 & -K^2 & -K^3 \\ K^1 & 0 & J^3 & -J^2 \\ K^2 & -J^3 & 0 & J^1 \\ K^3 & J^2 & -J^1 & 0 \end{pmatrix}. \quad (3.1)$$

$$[M^{\alpha\beta}, M^{\rho\sigma}] = -i(g^{\beta\sigma}M^{\alpha\rho} - g^{\beta\rho}M^{\alpha\sigma} + g^{\alpha\rho}M^{\beta\sigma} - g^{\alpha\sigma}M^{\beta\rho}) \quad (3.2)$$

There are  $\frac{n(n-1)}{2}$  number of planes in  $n$  dimension:

| Dimension | # of planes |
|-----------|-------------|
| 1D        | 0           |
| 2D        | 1           |
| 3D        | 3           |
| 4D        | 6           |
| 5D        | 10          |
| 6D        | 15          |

(3.3)

# Interpolating Manifestly Covariant Conformal Algebra (3 + 1)

We define the following  $6 \times 6$  tensor in the projective-space-time:

$$J_{\hat{a}, \hat{b}} = \begin{pmatrix} 0 & -D & -\frac{\hat{\mathfrak{K}}_{\hat{+}}}{\sqrt{2}} & -\frac{\hat{\mathfrak{K}}_{\hat{1}}}{\sqrt{2}} & -\frac{\hat{\mathfrak{K}}_{\hat{2}}}{\sqrt{2}} & -\frac{\hat{\mathfrak{K}}_{\hat{-}}}{\sqrt{2}} \\ D & 0 & \frac{P_{\hat{+}}}{\sqrt{2}} & \frac{P_{\hat{1}}}{\sqrt{2}} & \frac{P_{\hat{2}}}{\sqrt{2}} & \frac{P_{\hat{-}}}{\sqrt{2}} \\ \frac{\hat{\mathfrak{K}}_{\hat{+}}}{\sqrt{2}} & -\frac{P_{\hat{+}}}{\sqrt{2}} & 0 & \mathcal{D}^{\hat{1}} & \mathcal{D}^{\hat{2}} & K^3 \\ \frac{\hat{\mathfrak{K}}_{\hat{1}}}{\sqrt{2}} & -\frac{P_{\hat{1}}}{\sqrt{2}} & -\mathcal{D}^{\hat{1}} & 0 & J^3 & -\mathcal{K}^{\hat{1}} \\ \frac{\hat{\mathfrak{K}}_{\hat{2}}}{\sqrt{2}} & -\frac{P_{\hat{2}}}{\sqrt{2}} & -\mathcal{D}^{\hat{2}} & -J^3 & 0 & -\mathcal{K}^{\hat{2}} \\ \frac{\hat{\mathfrak{K}}_{\hat{-}}}{\sqrt{2}} & -\frac{P_{\hat{-}}}{\sqrt{2}} & -K^3 & \mathcal{K}^{\hat{1}} & \mathcal{K}^{\hat{2}} & 0 \end{pmatrix}_{(6 \times 6)} \quad (3.4)$$

Then, the simplified conformal algebra in interpolation is:

$$[J_{\hat{a}\hat{b}}, J_{\hat{c}\hat{d}}] = -i (g_{\hat{b}\hat{d}} J_{\hat{a}\hat{c}} - g_{\hat{b}\hat{c}} J_{\hat{a}\hat{d}} + g_{\hat{a}\hat{c}} J_{\hat{b}\hat{d}} - g_{\hat{a}\hat{d}} J_{\hat{b}\hat{c}}) \quad (3.5)$$

where,

$$g_{\hat{a}, \hat{b}} = \begin{pmatrix} 0 & -1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \mathcal{C} & 0 & 0 & \mathcal{S} \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & \mathcal{S} & 0 & 0 & -\mathcal{C} \end{pmatrix}_{6 \times 6} \quad (3.6)$$

# Isomorphism with Dirac matrices

Dirac<sup>3</sup> has shown the existence of isomorphism between  $SO(4, 2)$  conformal group and Dirac matrices. Later, Hepner<sup>4</sup> has explicitly shown the isomorphism between the group of Dirac's four-row  $\gamma$ -matrices and the continuous conformal group in Euclidean space.

We show

$$J'_{a,b} = \begin{pmatrix} 0 & \gamma_5 & \frac{(1-\gamma_5)\gamma_0}{\sqrt{2}} & \frac{(1-\gamma_5)\gamma_1}{\sqrt{2}} & \frac{(1-\gamma_5)\gamma_2}{\sqrt{2}} & \frac{(1-\gamma_5)\gamma_3}{\sqrt{2}} \\ -\gamma_5 & 0 & \frac{(1+\gamma_5)\gamma_0}{\sqrt{2}} & \frac{(1+\gamma_5)\gamma_1}{\sqrt{2}} & \frac{(1+\gamma_5)\gamma_2}{\sqrt{2}} & \frac{(1+\gamma_5)\gamma_3}{\sqrt{2}} \\ \frac{-(1-\gamma_5)\gamma_0}{\sqrt{2}} & \frac{-(1+\gamma_5)\gamma_0}{\sqrt{2}} & 0 & \gamma_0\gamma_1 & \gamma_0\gamma_2 & \gamma_0\gamma_3 \\ \frac{-(1-\gamma_5)\gamma_1}{\sqrt{2}} & \frac{-(1+\gamma_5)\gamma_1}{\sqrt{2}} & \gamma_1\gamma_0 & 0 & \gamma_1\gamma_2 & \gamma_1\gamma_3 \\ \frac{-(1-\gamma_5)\gamma_2}{\sqrt{2}} & \frac{-(1+\gamma_5)\gamma_2}{\sqrt{2}} & \gamma_2\gamma_0 & \gamma_2\gamma_1 & 0 & \gamma_2\gamma_3 \\ \frac{-(1-\gamma_5)\gamma_3}{\sqrt{2}} & \frac{-(1+\gamma_5)\gamma_3}{\sqrt{2}} & \gamma_3\gamma_0 & \gamma_3\gamma_1 & \gamma_3\gamma_2 & 0 \end{pmatrix}. \quad (3.7)$$

This  $J'_{a,b}$  obeys the  $SO(4 + 1, 1)$  algebra

$$[J_{ab}, J_{cd}] = -i (g_{bd}J_{ac} - g_{bc}J_{ad} + g_{ac}J_{bd} - g_{ad}J_{bc})$$

<sup>3</sup>Dirac, P. A. M. *Annals Math.* 37, 429–442 (1936)

<sup>4</sup>Hepner, W. A. *Nuovo Cim.* 26, 351–368 (1962).

# Isomorphism with Dirac matrices

The representation of the conformal group in terms of  $4 \times 4$  gamma matrices are the following;

$$P_\mu = \frac{i}{2}(1 + \gamma_5)\gamma_\mu; \quad (3.8)$$

$$\mathfrak{K}_\mu = \frac{-i}{2}(1 - \gamma_5)\gamma_\mu; \quad (3.9)$$

$$K^1 = \frac{i}{2}\gamma_1\gamma_0; \quad K^2 = \frac{i}{2}\gamma_2\gamma_0; \quad K^3 = \frac{i}{2}\gamma_3\gamma_0; \quad (3.10)$$

$$J^1 = \frac{i}{2}\gamma_2\gamma_3; \quad J^2 = \frac{i}{2}\gamma_3\gamma_1; \quad J^3 = \frac{i}{2}\gamma_1\gamma_2; \quad (3.11)$$

$$D = \frac{-i}{2}\gamma_5. \quad (3.12)$$

# Interpolating Manifestly Covariant Conformal Algebra (1 + 1)

We have:

$$J_{\hat{a}\hat{b}} = \begin{pmatrix} 0 & -D & -\frac{\hat{R}_+}{\sqrt{2}} & -\frac{\hat{R}_-}{\sqrt{2}} \\ D & 0 & \frac{P_+}{\sqrt{2}} & \frac{P_-}{\sqrt{2}} \\ \frac{\hat{R}_+}{\sqrt{2}} & -\frac{P_+}{\sqrt{2}} & 0 & K^{-3} \\ \frac{\hat{R}_-}{\sqrt{2}} & -\frac{P_-}{\sqrt{2}} & -K^{-3} & 0 \end{pmatrix}_{(4 \times 4)} \quad (4.1)$$

Then, the 1 + 1 conformal algebra in LFD is given by

$$[J_{\hat{a}\hat{b}}, J_{\hat{c}\hat{d}}] = -i (g_{\hat{b}\hat{d}} J_{\hat{a}\hat{c}} - g_{\hat{b}\hat{c}} J_{\hat{a}\hat{d}} + g_{\hat{a}\hat{c}} J_{\hat{b}\hat{d}} - g_{\hat{a}\hat{d}} J_{\hat{b}\hat{c}}) \quad (4.2)$$

where,

$$g_{\hat{a}\hat{b}} = \begin{pmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & \mathbb{C} & \mathbb{S} \\ 0 & 0 & \mathbb{S} & -\mathbb{C} \end{pmatrix}_{4 \times 4} \quad (4.3)$$

From (4.2), one can write

$$J_{\hat{a}\hat{b}} = i(x_{\hat{a}} \partial_{\hat{b}} - x_{\hat{b}} \partial_{\hat{a}}) \quad (4.4)$$

where  $\hat{a}, \hat{b} \in \{-2, -1, \hat{+}, \hat{-}\}$ .

# Interpolating Manifestly Covariant Conformal Algebra (1 + 1)

Let's say that  $A^{\hat{a}}$  is hyper-4-vector; suppose  $A^{\hat{a}}$  and  $B^a$  transform under 6d rotation:

$$A'^{\hat{a}} = R^{\hat{a}}_{\hat{b}} A^{\hat{b}}, \quad B'^{\hat{a}} = R^{\hat{a}}_{\hat{b}} B^{\hat{b}}. \quad (4.5)$$

Then the inner products  $A' \cdot B'$  and  $A \cdot B$  can be written as

$$A'_i B'^{\hat{b}} = (g_{\hat{a}\hat{b}} R^{\hat{a}}_{\hat{c}} R^{\hat{b}}_{\hat{d}}) A^{\hat{c}} B^{\hat{d}}, \quad (4.6)$$

$$A_i B^{\hat{b}} = g_{\hat{c}\hat{d}} A^{\hat{c}} B^{\hat{d}}. \quad (4.7)$$

In order for  $A' \cdot B' = A \cdot B$  to hold for any  $A$  and  $B$ , the coefficients of  $A^{\hat{c}} B^{\hat{d}}$  should be the same term by term:

$$g_{\hat{a}\hat{b}} R^{\hat{a}}_{\hat{c}} R^{\hat{b}}_{\hat{d}} = g_{\hat{c}\hat{d}}. \quad (4.8)$$

Let's start by looking at a hyper-4d rotation transformation, which is (has to be) infinitesimally close to the identity:

$$R^{\hat{a}}_{\hat{b}} = g^{\hat{a}}_{\hat{b}} + \omega^{\hat{a}}_{\hat{b}}, \quad (4.9)$$

where  $\omega^{\hat{a}}_{\hat{b}}$  is a set of small (real) numbers.

# Interpolating Manifestly Covariant Conformal Algebra (1 + 1)

Inserting this into the defining condition, we get

$$g^{\hat{c}\hat{d}} = R^{\hat{c}}_{\hat{b}} R^{\hat{b}\hat{d}}, \quad (4.10)$$

$$\begin{aligned} &= (g^{\hat{c}}_{\hat{b}} + \omega^{\hat{c}}_{\hat{b}})(g^{\hat{b}\hat{d}} + \omega^{\hat{b}\hat{d}}), \\ &= g^{\hat{c}\hat{d}} + \omega^{\hat{c}\hat{d}} + \omega^{\hat{d}\hat{c}} + \mathcal{O}(\omega^2). \end{aligned} \quad (4.11)$$

Keeping terms to the first order in  $\omega$ , we then obtain

$$\omega^{\hat{a}\hat{b}} = -\omega^{\hat{b}\hat{a}}. \quad (4.12)$$

Thus, it has 6 independent parameters:

$$\omega^{\hat{a}\hat{b}} = \begin{pmatrix} 0 & \omega^{-2, \hat{-1}} & \omega^{-2, \hat{+}} & \omega^{-2, \hat{-}} \\ -\omega^{-2, \hat{-1}} & 0 & \omega^{-1, \hat{+}} & \omega^{-1, \hat{-}} \\ -\omega^{-2, \hat{+}} & -\omega^{-1, \hat{+}} & 0 & \omega^{\hat{+}, \hat{-}} \\ -\omega^{-2, \hat{-}} & -\omega^{\hat{+}, \hat{-}} & -\omega^{\hat{+}, \hat{-}} & 0 \end{pmatrix}_{(4 \times 4)}. \quad (4.13)$$

This can be conveniently parameterized using 6 anti-symmetric matrices as

$$\omega^{\hat{a}\hat{b}} = -i \sum_{\hat{c} < \hat{d}} \omega^{\hat{c}\hat{d}} (J_{\hat{c}\hat{d}})^{\hat{a}\hat{b}}, \quad (4.14)$$

# Interpolating Manifestly Covariant Conformal Algebra (1 + 1)

where

$$(J_{\hat{c}\hat{d}})^{\hat{a}\hat{b}} = i(g_{\hat{c}\hat{e}}^{\hat{a}}g_{\hat{d}}^{\hat{b}} - g_{\hat{e}\hat{d}}^{\hat{b}}g_{\hat{c}}^{\hat{a}}). \quad (4.15)$$

then

$$\omega^{\hat{a}\hat{b}} = -i \sum_{\hat{c} < \hat{d}} \omega^{\hat{c}\hat{d}} (J_{\hat{c}\hat{d}})^{\hat{a}\hat{b}} = -i \sum_{\hat{c} > \hat{d}} \omega^{\hat{c}\hat{d}} (J_{\hat{c}\hat{d}})^{\hat{a}\hat{b}} = -\frac{i}{2} \omega^{\hat{c}\hat{d}} (J_{\hat{c}\hat{d}})^{\hat{a}\hat{b}}, \quad (4.16)$$

where in the last expression, the sum over all values of  $\hat{c}$  and  $\hat{d}$  is implied. The infinitesimal transformation (hyper-4d rotation) ((??)) can then be written a

$$R_{\hat{b}}^{\hat{a}} = g_{\hat{b}}^{\hat{a}} - \frac{i}{2} \omega^{\hat{c}\hat{d}} (J_{\hat{c}\hat{d}})_{\hat{b}}^{\hat{a}}, \quad (4.17)$$

The generator representation  $(J_{\hat{c}\hat{d}})_{\hat{b}}^{\hat{a}}$  can be obtained by

$$(J_{\hat{c}\hat{d}})_{\hat{b}}^{\hat{a}} = (J_{\hat{c}\hat{d}})^{\hat{a}\hat{f}} g_{\hat{f}\hat{b}} \quad (4.18)$$



# Interpolating Manifestly Covariant Conformal Algebra (1 + 1)

The representation matrices of conformal generators are defined by taking the first index to be superscript and the second subscript:

$$\frac{-\mathfrak{K}_{\hat{\mu}}}{\sqrt{2}} \equiv (J_{\hat{-}2\hat{\mu}})^{\hat{a}}_{\hat{b}} ; \quad \frac{P_{\hat{\mu}}}{\sqrt{2}} \equiv (J_{\hat{-}1\hat{\mu}})^{\hat{a}}_{\hat{b}} ; \quad -D \equiv (J_{\hat{-}2\hat{-}1})^{\hat{a}}_{\hat{b}} ; \quad K^3 \equiv (J_{\hat{+},\hat{-}})^{\hat{a}}_{\hat{b}}. \quad (4.19)$$

where  $a, b \in \{-2, -1, \hat{+}, \hat{-}\}$  and  $\mu \in \{\hat{+}, \hat{-}\}$ .

Explicitly,

$$\begin{aligned} \mathfrak{K}_{\hat{+}} &= \sqrt{2} \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & i & 0 \\ i\mathbb{C} & 0 & 0 & 0 \\ i\mathbb{S} & 0 & 0 & 0 \end{pmatrix} ; & \mathfrak{K}_{\hat{-}} &= \sqrt{2} \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & i \\ i\mathbb{S} & 0 & 0 & 0 \\ -i\mathbb{C} & 0 & 0 & 0 \end{pmatrix} ; & D &= \begin{pmatrix} -i & 0 & 0 & 0 \\ 0 & i & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \\ P_{\hat{+}} &= \sqrt{2} \begin{pmatrix} 0 & 0 & -i & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -i\mathbb{C} & 0 & 0 \\ 0 & -i\mathbb{S} & 0 & 0 \end{pmatrix} ; & P_{\hat{-}} &= \sqrt{2} \begin{pmatrix} 0 & 0 & 0 & -i \\ 0 & 0 & 0 & 0 \\ 0 & -i\mathbb{S} & 0 & 0 \\ 0 & i\mathbb{C} & 0 & 0 \end{pmatrix} ; & K^3 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -i\mathbb{S} & i\mathbb{C} \\ 0 & 0 & i\mathbb{C} & i\mathbb{S} \end{pmatrix} \quad (4.20) \end{aligned}$$

# Interpolating Manifestly Covariant Conformal Algebra (1 + 1)

We define the conformal transformations in interpolation as those transformations preserving the light cone. This is equivalent to preserving angles and also equivalent to preserving ratios of lengths. Let's consider a hyper-4d vector;

$$\tilde{x}_{\hat{-1}} = \frac{-\lambda}{\sqrt{2}}; \quad (4.21)$$

$$\tilde{x}_{\hat{-2}} = \frac{-\lambda}{\sqrt{2}}(x^{\hat{\mu}} \cdot x_{\hat{\mu}}); \quad (4.22)$$

$$\tilde{x}_{\hat{\mu}} = \lambda x_{\hat{\mu}}; \quad (4.23)$$

Now, let's consider the hyper-4d dot product,

$$g_{\hat{a}\hat{b}} \tilde{x}^{\hat{a}} \tilde{x}^{\hat{b}} = \tilde{x}^{\hat{-2}} \tilde{x}_{\hat{-2}} + \tilde{x}^{\hat{-1}} \tilde{x}_{\hat{-1}} + \tilde{x}^{\hat{\mu}} \tilde{x}_{\hat{\mu}} \quad (4.24)$$

$$\tilde{x}_{\hat{a}} \cdot \tilde{x}^{\hat{a}} = -2\tilde{x}_{\hat{-2}} \tilde{x}_{\hat{-1}} + \tilde{x}^{\hat{\mu}} \tilde{x}_{\hat{\mu}} \quad (\because \tilde{x}_{\hat{-1}} = -\tilde{x}^{\hat{-2}} \text{ \& } \tilde{x}_{\hat{-2}} = -\tilde{x}^{\hat{-1}}) \quad (4.25)$$

$$\tilde{x}_{\hat{a}} \cdot \tilde{x}^{\hat{a}} = -2 \frac{-\lambda}{\sqrt{2}}(x^{\hat{\mu}} \cdot x_{\hat{\mu}}) \frac{-\lambda}{\sqrt{2}} + \lambda^2 x^{\hat{\mu}} x_{\hat{\mu}} = -\lambda^2 x^{\hat{\mu}} x_{\hat{\mu}} + \lambda^2 x^{\hat{\mu}} x_{\hat{\mu}} \quad (4.26)$$

$$\tilde{x}_{\hat{a}} \cdot \tilde{x}^{\hat{a}} = 0 \quad (4.27)$$

# Interpolating Manifestly Covariant Conformal Algebra (1 + 1)

then,

$$\boxed{x_{\hat{\mu}} = -\frac{1}{\sqrt{2}} \frac{\tilde{x}_{\hat{\mu}}}{\tilde{x}_{\hat{-1}}}} \quad (4.28)$$

$$\boxed{\frac{x_{\hat{\mu}}}{x^2}} = -\frac{1}{\sqrt{2}} \frac{\tilde{x}_{\hat{\mu}}}{\tilde{x}_{\hat{-1}}} \frac{2\tilde{x}_{\hat{-1}}\tilde{x}_{\hat{-1}}}{\tilde{x}_{\hat{\mu}}\tilde{x}^{\hat{\mu}}} = -\frac{1}{\sqrt{2}} \frac{\tilde{x}_{\hat{\mu}}}{\tilde{x}_{\hat{-1}}} \frac{2\tilde{x}_{\hat{-1}}\tilde{x}_{\hat{-1}}}{2\tilde{x}_{\hat{-2}}\tilde{x}_{\hat{-1}}} = \boxed{-\frac{1}{\sqrt{2}} \frac{\tilde{x}_{\hat{\mu}}}{\tilde{x}_{\hat{-2}}}} \quad (4.29)$$

Also,  $\boxed{x^2 = \frac{\tilde{x}_{\hat{-2}}}{\tilde{x}_{\hat{-1}}}}$ .

Let's find the space-time transformation under each conformal generators in 1 + 1.

# Interpolating Manifestly Covariant Conformal Algebra (1 + 1)

For  $\mathfrak{K}_{\hat{\dagger}}$ :

$$\begin{pmatrix} \tilde{x}'_{\hat{-}2} \\ \tilde{x}'_{\hat{-}1} \\ \tilde{x}'_{\hat{\dagger}} \\ \tilde{x}'_{\hat{-}} \end{pmatrix} = \exp(-ib^{\hat{\dagger}} \mathfrak{K}_{\hat{\dagger}}) \begin{pmatrix} \tilde{x}_{\hat{-}2} \\ \tilde{x}_{\hat{-}1} \\ \tilde{x}_{\hat{\dagger}} \\ \tilde{x}_{\hat{-}} \end{pmatrix} \quad (4.30)$$

$$\begin{pmatrix} \tilde{x}'_{\hat{-}2} \\ \tilde{x}'_{\hat{-}1} \\ \tilde{x}'_{\hat{\dagger}} \\ \tilde{x}'_{\hat{-}} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ \mathbb{C}(b^{\hat{\dagger}})^2 & 1 & \sqrt{2}b^{\hat{\dagger}} & 0 \\ \sqrt{2}\mathbb{C}b^{\hat{\dagger}} & 0 & 1 & 0 \\ \sqrt{2}\mathbb{S}b^{\hat{\dagger}} & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \tilde{x}_{\hat{-}2} \\ \tilde{x}_{\hat{-}1} \\ \tilde{x}_{\hat{\dagger}} \\ \tilde{x}_{\hat{-}} \end{pmatrix} \quad (4.31)$$

$$\begin{pmatrix} \tilde{x}'_{\hat{-}2} \\ \tilde{x}'_{\hat{-}1} \\ \tilde{x}'_{\hat{\dagger}} \\ \tilde{x}'_{\hat{-}} \end{pmatrix} = \begin{pmatrix} \tilde{x}_{\hat{-}2} \\ \mathbb{C}(b^{\hat{\dagger}})^2 \tilde{x}_{\hat{-}2} + \tilde{x}_{\hat{-}1} + \sqrt{2}b^{\hat{\dagger}} \tilde{x}_{\hat{\dagger}} \\ \sqrt{2}\mathbb{C}b^{\hat{\dagger}} \tilde{x}_{\hat{-}2} + \tilde{x}_{\hat{\dagger}} \\ \sqrt{2}\mathbb{S}b^{\hat{\dagger}} \tilde{x}_{\hat{-}2} + \tilde{x}_{\hat{-}} \end{pmatrix} \quad (4.32)$$

# Interpolating Manifestly Covariant Conformal Algebra (1 + 1)

On space-time, this transformation gives

$$x'_{\hat{+}} = \frac{-1}{\sqrt{2}} \frac{\tilde{x}'_{\hat{+}}}{\tilde{x}'_{\hat{-}1}} \quad (4.33)$$

$$= \frac{-1}{\sqrt{2}} \frac{\mathbb{C}b^{\hat{+}}\tilde{x}_{\hat{-}2} + \tilde{x}_{\hat{+}}}{\mathbb{C}(b^{\hat{+}})^2\tilde{x}_{\hat{-}2} + \tilde{x}_{\hat{-}1} + \sqrt{2}b^{\hat{+}}\tilde{x}_{\hat{+}}} \quad (4.34)$$

$$= \frac{-1}{\sqrt{2}} \frac{\mathbb{C}b^{\hat{+}}\frac{\tilde{x}_{\hat{-}2}}{\tilde{x}_{\hat{-}1}} + \frac{\tilde{x}_{\hat{+}}}{\tilde{x}_{\hat{-}1}}}{\mathbb{C}(b^{\hat{+}})^2\frac{\tilde{x}_{\hat{-}2}}{\tilde{x}_{\hat{-}1}} + 1 + \sqrt{2}b^{\hat{+}}\frac{\tilde{x}_{\hat{+}}}{\tilde{x}_{\hat{-}1}}} \quad (4.35)$$

$$= -\frac{1}{\sqrt{2}} \frac{\mathbb{C}b^{\hat{+}}x^2 + (-\sqrt{2}x_{\hat{+}})}{\mathbb{C}(b^{\hat{+}})^2x^2 + 1 + \sqrt{2}b^{\hat{+}}(-\sqrt{2}x_{\hat{+}})} \quad (4.36)$$

$$x'_{\hat{+}} = \frac{x_{\hat{+}} - \mathbb{C}b^{\hat{+}}x^2}{1 - 2b^{\hat{+}}x_{\hat{+}} + \mathbb{C}(b^{\hat{+}})^2x^2} \quad (4.37)$$

# Transformation of $x_{\hat{\pm}}$ under conformal transformation

In the interpolation form:

| Generators               | $x'_{\hat{+}}$   | $x'_{\hat{-}}$   |
|--------------------------|--|--|
| $\mathfrak{K}_{\hat{+}}$ | $x'_{\hat{+}} = \frac{x_{\hat{+}} - \mathbb{C}b^{\hat{+}}x^2}{1 - 2b^{\hat{+}}x_{\hat{+}} + \mathbb{C}(b^{\hat{+}})^2x^2}$ | $x'_{\hat{-}} = \frac{x_{\hat{-}} - \mathbb{S}b^{\hat{+}}x^2}{1 - 2b^{\hat{+}}x_{\hat{+}} + \mathbb{C}(b^{\hat{+}})^2x^2}$ |
| $\mathfrak{K}_{\hat{-}}$ | $x'_{\hat{+}} = \frac{x_{\hat{+}} - \mathbb{S}b^{\hat{-}}x^2}{1 - 2b^{\hat{-}}x_{\hat{-}} - \mathbb{C}(b^{\hat{-}})^2x^2}$ | $x'_{\hat{-}} = \frac{x_{\hat{-}} + \mathbb{C}b^{\hat{-}}x^2}{1 - 2b^{\hat{-}}x_{\hat{-}} - \mathbb{C}(b^{\hat{-}})^2x^2}$ |
| $P_{\hat{+}}$            | $x'_{\hat{+}} = x_{\hat{+}} + \mathbb{C}a^{\hat{+}}$   | $x'_{\hat{-}} = x_{\hat{-}} + \mathbb{S}a^{\hat{+}}$   |
| $P_{\hat{-}}$            | $x'_{\hat{+}} = x_{\hat{+}} + \mathbb{S}a^{\hat{-}}$   | $x'_{\hat{-}} = x_{\hat{-}} - \mathbb{C}a^{\hat{-}}$   |
| $D$                      | $x'_{\hat{+}} = e^{-\alpha}x_{\hat{+}}$  | $x'_{\hat{-}} = e^{-\alpha}x_{\hat{-}}$  |
| $K^3$                    | $x'_{\hat{+}} = (\cosh \eta_3 - \mathbb{S} \sinh \eta_3)x_{\hat{+}} + (\mathbb{C} \sinh \eta_3)x_{\hat{-}}$                | $x'_{\hat{-}} = (\mathbb{C} \sinh \eta_3)x_{\hat{+}} + (\cosh \eta_3 + \mathbb{S} \sinh \eta_3)x_{\hat{-}}$                |

where,  $x_{\hat{+}} = x_0 \cos \delta + x_3 \sin \delta$ , and  $x_{\hat{-}} = x_0 \sin \delta - x_3 \cos \delta$

# Transformation of $x_0$ and $x_3$ under conformal transformation

In the instant form limit:  $\delta \rightarrow 0$ ,  $\mathbb{S} \rightarrow 0$ , and  $\mathbb{C} \rightarrow 1$ .

| Generators        | $x'_0$  | $x'_3$  |
|-------------------|---|---|
| $\mathfrak{K}_0$  | $x'_0 = \frac{x_0 - b_0 x^2}{1 - 2b_0 x_0 + (b_0)^2 x^2}$ | $x'_3 = \frac{x_3}{1 - 2b_0 x_0 + (b_0)^2 x^2}$           |
| $-\mathfrak{K}_3$ | $x'_0 = \frac{x_0}{1 - 2b_3 x_0 - (b_3)^2 x^2}$           | $x'_3 = \frac{x_3 + b_3 x^2}{1 - 2b_3 x_0 - (b_3)^2 x^2}$ |
| $P_0$             | $x'_0 = x_0 + a_0$  | $x'_3 = x_3$  |
| $-P_3$            | $x'_0 = x_0$  | $x'_3 = x_3 - a_3$  |
| $D$               | $x'_0 = e^{-\alpha} x_0$                                  | $x'_3 = e^{-\alpha} x_3$                                  |
| $K^3$             | $x'_0 = (\cosh \eta_3) x_0 - (\sinh \eta_3) x_3$          | $x'_3 = -(\sinh \eta_3) x_0 + (\cosh \eta_3) x_3$         |

# Transformation of $x_{\pm}$ under conformal transformation

In the light front limit:  $\delta \rightarrow \frac{\pi}{4}$ ,  $\mathbb{C} \rightarrow 0$ , and  $\mathbb{S} \rightarrow 1$ .

| Generators       | $x'_+$                                    | $x'_-$                                    |
|------------------|---|---|
| $\mathfrak{K}_+$ | $x'_+ = \frac{x_+}{1 - 2b^+x_+}$          | $x'_- = x_-$                              |
| $\mathfrak{K}_-$ | $x'_+ = x_+$                              | $x'_- = \frac{x_-}{1 - 2b^-x_-}$          |
| $P_+$            | $x'_+ = x_+$                              | $x'_- = x_- + a^+$                        |
| $P_-$            | $x'_+ = x_+ + a^-$                        | $x'_- = x_-$                              |
| $D$              | $x'_+ = e^{-\alpha}x_+$                   | $x'_- = e^{-\alpha}x_-$                   |
| $K^3$            | $x'_+ = (\cosh \eta_3 - \sinh \eta_3)x_+$ | $x'_- = (\cosh \eta_3 + \sinh \eta_3)x_-$ |

where,  $x_+ = \frac{x_0 + x_3}{\sqrt{2}}$ , and  $x_- = \frac{x_0 - x_3}{\sqrt{2}}$



## Interpolating $D$ and $K^3$

Let's introduce the interpolating  $D_{\hat{\uparrow}}$  and  $D_{\hat{\downarrow}}$  as:

$$\begin{bmatrix} D_{\hat{\uparrow}} \\ D_{\hat{\downarrow}} \end{bmatrix} = \begin{bmatrix} \cos \delta & \sin \delta \\ \sin \delta & -\cos \delta \end{bmatrix} \begin{bmatrix} D \\ K^3 \end{bmatrix} \quad (5.1)$$

therefore,

$$D_{\hat{\uparrow}} = \cos \delta D + \sin \delta K^3, \quad (5.2)$$

$$D_{\hat{\downarrow}} = \sin \delta D - \cos \delta K^3. \quad (5.3)$$

We can also write

$$\begin{bmatrix} D \\ K^3 \end{bmatrix} = \begin{bmatrix} \cos \delta & \sin \delta \\ \sin \delta & -\cos \delta \end{bmatrix} \begin{bmatrix} D_{\hat{\uparrow}} \\ D_{\hat{\downarrow}} \end{bmatrix} \quad (5.4)$$

therefore,

$$D = \cos \delta D_{\hat{\uparrow}} + \sin \delta D_{\hat{\downarrow}}, \quad (5.5)$$

$$K^3 = \sin \delta D_{\hat{\uparrow}} - \cos \delta D_{\hat{\downarrow}}. \quad (5.6)$$

# Interpolating $D$ and $K^3$

The commutation relations among all interpolating conformal generators in two dimensional are given below:

Table 1: 1 + 1 conformal algebra in the interpolation form.

|                 | $P_+$  | $\mathcal{R}_-$   | $D_-$  | $P_-$  | $\mathcal{R}_+$   | $D_+$  |
|-----------------|--|---|--|--|---|--|
| $P_+$           | 0  | $2i((\mathbb{S} \cos \delta - \mathbb{S} \sin \delta)D_+ + (\mathbb{S} \sin \delta + \mathbb{C} \cos \delta)D_-)$ | $i((\sin \delta + \mathbb{S} \cos \delta)P_+ - \mathbb{C} \cos \delta P_-)$                      | 0  | $2i\mathbb{C}(\cos \delta D_+ + \sin \delta D_-)$   | $i((\cos \delta - \mathbb{S} \sin \delta)P_+ + \mathbb{C} \sin \delta P_-)$                      |
| $\mathcal{R}_-$ | $-2i((\mathbb{S} \cos \delta - \sin \delta)D_+ + (\mathbb{S} \sin \delta + \cos \delta)D_-)$ | 0   | $-i((\sin \delta + \mathbb{S} \cos \delta)\mathcal{R}_+ + \mathbb{C} \cos \delta \mathcal{R}_-)$ | $2i\mathbb{C}(\cos \delta D_+ + \sin \delta D_-)$  | 0   | $-i((\cos \delta - \mathbb{S} \sin \delta)\mathcal{R}_+ - \mathbb{C} \sin \delta \mathcal{R}_-)$ |
| $D_-$           | $-i((\sin \delta + \mathbb{S} \cos \delta)P_+ - \mathbb{C} \cos \delta P_-)$                 | $i((\sin \delta + \mathbb{S} \cos \delta)\mathcal{R}_+ + \mathbb{C} \cos \delta \mathcal{R}_-)$                   | 0  | $-i((\sin \delta - \mathbb{S} \cos \delta)P_- - \mathbb{C} \cos \delta P_+)$                 | $i((\sin \delta - \mathbb{S} \cos \delta)\mathcal{R}_+ + \mathbb{C} \cos \delta \mathcal{R}_-)$ | 0  |
| $P_-$           | 0  | $-2i\mathbb{C}(\cos \delta D_+ + \sin \delta D_-)$  | $i((\sin \delta - \mathbb{S} \cos \delta)P_- - \mathbb{C} \cos \delta P_+)$                      | 0  | $2i((\mathbb{S} \cos \delta + \sin \delta)D_+ + (\mathbb{S} \sin \delta - \cos \delta)D_-)$     | $i((\cos \delta + \mathbb{S} \sin \delta)P_- + \mathbb{C} \sin \delta P_+)$                      |
| $\mathcal{R}_+$ | $-2i\mathbb{C}(\cos \delta D_+ + \sin \delta D_-)$   | 0   | $-i((\sin \delta - \mathbb{S} \cos \delta)\mathcal{R}_+ + \mathbb{C} \cos \delta \mathcal{R}_-)$ | $-2i((\mathbb{S} \cos \delta + \sin \delta)D_+ + (\mathbb{S} \sin \delta - \cos \delta)D_-)$ | 0   | $-i((\cos \delta + \mathbb{S} \sin \delta)\mathcal{R}_+ - \mathbb{C} \sin \delta \mathcal{R}_-)$ |
| $D_+$           | $-i((\cos \delta - \mathbb{S} \sin \delta)P_+ + \mathbb{C} \sin \delta P_-)$                 | $i((\cos \delta - \mathbb{S} \sin \delta)\mathcal{R}_+ - \mathbb{C} \sin \delta \mathcal{R}_-)$                   | 0  | $-i((\cos \delta + \mathbb{S} \sin \delta)P_- + \mathbb{C} \sin \delta P_+)$                 | $i((\cos \delta + \mathbb{S} \sin \delta)\mathcal{R}_+ - \mathbb{C} \sin \delta \mathcal{R}_-)$ | 0  |

# Interpolating $D$ and $K^3$

In the limit  $\delta \rightarrow 0$ , we recover the commutation relations among all instant form conformal generators in two dimensional as given below:

Table 2: 1 + 1 conformal algebra in IFD

|                   | $P_0$   | $-\mathfrak{K}_3$  | $-K^3$             | $-P_3$   | $\mathfrak{K}_0$   | $D$                |
|-------------------|---------|--------------------|--------------------|----------|--------------------|--------------------|
| $P_0$             | 0       | $-2iK^3$           | $iP_3$             | 0        | $2iD$              | $iP_0$             |
| $-\mathfrak{K}_3$ | $2iK^3$ | 0                  | $-i\mathfrak{K}_0$ | $2iD$    | 0                  | $i\mathfrak{K}_3$  |
| $-K^3$            | $-iP_3$ | $i\mathfrak{K}_0$  | 0                  | $iP_0$   | $-i\mathfrak{K}_3$ | 0                  |
| $-P_3$            | 0       | $-2iD$             | $-iP_0$            | 0        | $2iK^3$            | $-iP_3$            |
| $\mathfrak{K}_0$  | $-2iD$  | 0                  | $i\mathfrak{K}_3$  | $-2iK^3$ | 0                  | $-i\mathfrak{K}_0$ |
| $D$               | $-iP_0$ | $-i\mathfrak{K}_3$ | 0                  | $iP_3$   | $i\mathfrak{K}_0$  | 0                  |

# Interpolating $D$ and $K^3$

In the limit  $\delta \rightarrow \frac{\pi}{4}$ , we recover the commutation relations among all light-front conformal generators in two dimensional as given below:

Table 3: 1 + 1 conformal algebra in LFD

|                  | $P_+$            | $\mathfrak{K}_-$          | $D_-$                      | $P_-$            | $\mathfrak{K}_+$          | $D_+$                      |
|------------------|------------------|---------------------------|----------------------------|------------------|---------------------------|----------------------------|
| $P_+$            | 0                | $2\sqrt{2}iD_-$           | $\sqrt{2}iP_+$             | 0                | 0                         | 0                          |
| $\mathfrak{K}_-$ | $-2\sqrt{2}iD_-$ | 0                         | $-\sqrt{2}i\mathfrak{K}_-$ | 0                | 0                         | 0                          |
| $D_-$            | $-\sqrt{2}iP_+$  | $\sqrt{2}i\mathfrak{K}_-$ | 0                          | 0                | 0                         | 0                          |
| $P_-$            | 0                | 0                         | 0                          | 0                | $2\sqrt{2}iD_+$           | $\sqrt{2}iP_-$             |
| $\mathfrak{K}_+$ | 0                | 0                         | 0                          | $-2\sqrt{2}iD_+$ | 0                         | $-\sqrt{2}i\mathfrak{K}_+$ |
| $D_+$            | 0                | 0                         | 0                          | $-\sqrt{2}iP_-$  | $\sqrt{2}i\mathfrak{K}_+$ | 0                          |

where,  $D_{\pm} = \frac{D \pm K^3}{\sqrt{2}}$ ,  $\mathfrak{K}_{\pm} = \frac{\mathfrak{K}_0 \pm \mathfrak{K}_3}{\sqrt{2}}$ , and  $P_{\pm} = \frac{P_0 \pm P_3}{\sqrt{2}}$ .

# Interpolating $D$ and $K^3$

We find<sup>5</sup> that  $SO(2, 2)$  splits into a direct sum of two identical algebras:

$$SO(2, 2) \simeq SO(1, 2) \oplus SO(1, 2) \quad (5.7)$$

Lets make two new  $3 \times 3$  anti symmetric tensors, namely  $J_{ab}^+$  and  $J_{ab}^-$ . Where,  $a, b \in \{0, 1, 2\}$ .

$$J_{ab}^+ = \frac{1}{2} \begin{pmatrix} 0 & P_+ & D-K^3 \\ -P_+ & 0 & \mathfrak{K}_- \\ -D+K^3 & -\mathfrak{K}_- & 0 \end{pmatrix}_{3 \times 3} ; \quad J_{ab}^- = \frac{1}{2} \begin{pmatrix} 0 & P_- & D+K^3 \\ -P_- & 0 & \mathfrak{K}_+ \\ -D-K^3 & -\mathfrak{K}_+ & 0 \end{pmatrix}_{3 \times 3} \quad (5.8)$$

and with the new metric  $g_{ab}$ ,

$$g_{ab} = \frac{1}{2} \begin{pmatrix} 0 & 0 & -1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix}_{3 \times 3} \quad (5.9)$$

they fulfill the  $SO(1, 2)$  commutation relations;

$$[J_{ab}^\pm, J_{cd}^\pm] = -i (g_{bd}J_{ac}^\pm - g_{bc}J_{ad}^\pm + g_{ac}J_{bd}^\pm - g_{ad}J_{bc}^\pm) ; \quad [J_{ab}^+, J_{cd}^-] = 0$$

These are perfectly consistent with the above table in the LFD limit.

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<sup>5</sup>Daniel Meise's Relations between 2D and 4D Conformal Quantum Field Theory

# Interpolating $D$ and $K^3$

Also, we have:

$$J_{a,b} = \begin{pmatrix} 0 & -D & -\frac{\mathfrak{K}_+}{\sqrt{2}} & -\frac{\mathfrak{K}_-}{\sqrt{2}} \\ D & 0 & \frac{P_+}{\sqrt{2}} & \frac{P_-}{\sqrt{2}} \\ \frac{\mathfrak{K}_+}{\sqrt{2}} & -\frac{P_+}{\sqrt{2}} & 0 & K^3 \\ \frac{\mathfrak{K}_-}{\sqrt{2}} & -\frac{P_-}{\sqrt{2}} & -K^3 & 0 \end{pmatrix}_{(4 \times 4)} \quad (5.10)$$

Then, the simplified conformal algebra in LFD is:

$$[J_{ab}, J_{cd}] = -i(g_{bd}J_{ac} - g_{bc}J_{ad} + g_{ac}J_{bd} - g_{ad}J_{bc}) \quad (5.11)$$

where,

$$g_{a,b} = \begin{pmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}_{4 \times 4} \quad (5.12)$$

# Current Progress

- Finding and verifying the basis for  $4 \times 4$  projective-space-time representations and  $4 \times 4$  gamma matrices (projective-space-time spinors) representations.
- Finding this new  $3 \times 3$  projective-space-time representations.
- Understanding the split in conformal algebra in LFD:  
 $SO(2, 2) \simeq SO(1, 2) \oplus SO(1, 2)$
- Connecting our calculations to some suitable physical process to extract the physics of the conformal group.